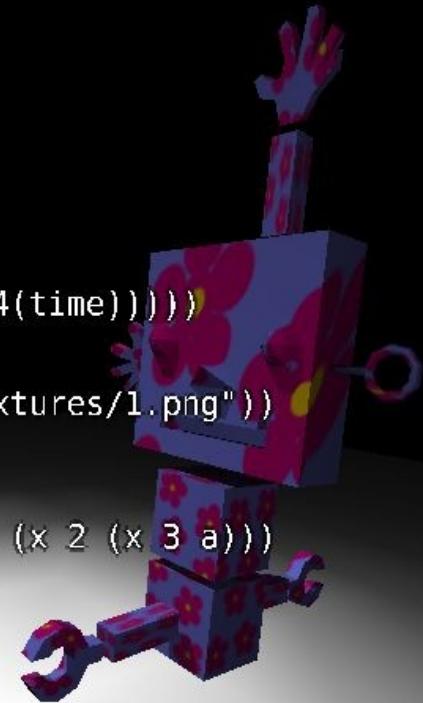
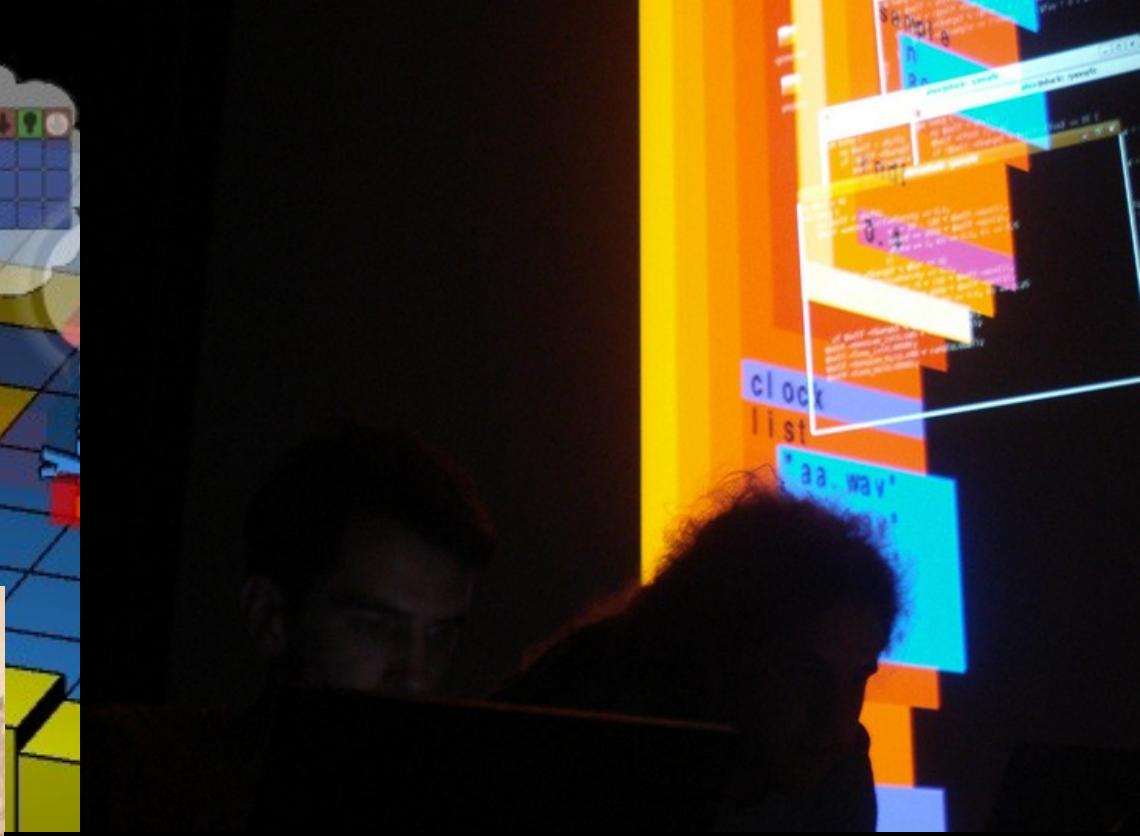


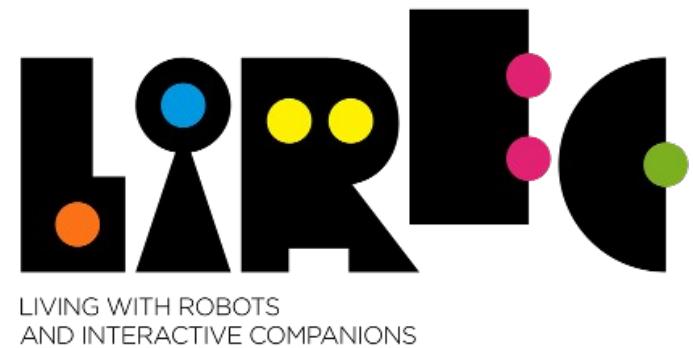
strange things people do with cameras  
dave griffiths





```
(require "lazybotz.scm")
(go-laziness)
(define (a) (* 45 (sin (* 4(time)))))
(define (a) (* 45 ))
(texture (load-texture "textures/1.png"))
(bot 'fred
  (x 0
    (x 4 (x 2) (x 3 a) (x 2 (x 3 a)))
    (x 0
      (x 2 (x 4))
      (x 2 (x 4)))
    (x 0))) "go))
```





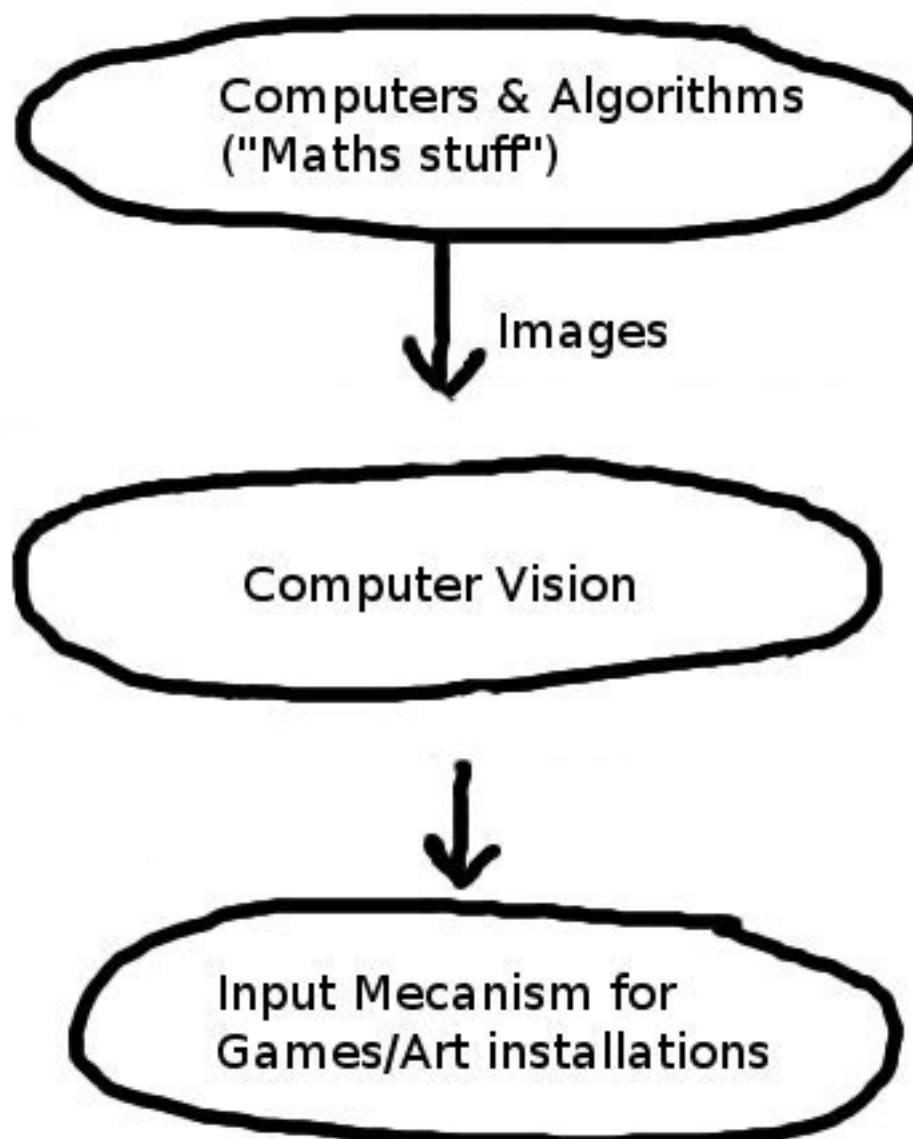
computer vision  
or  
algorithmic understanding of images

# what has this got to do with computational photography?

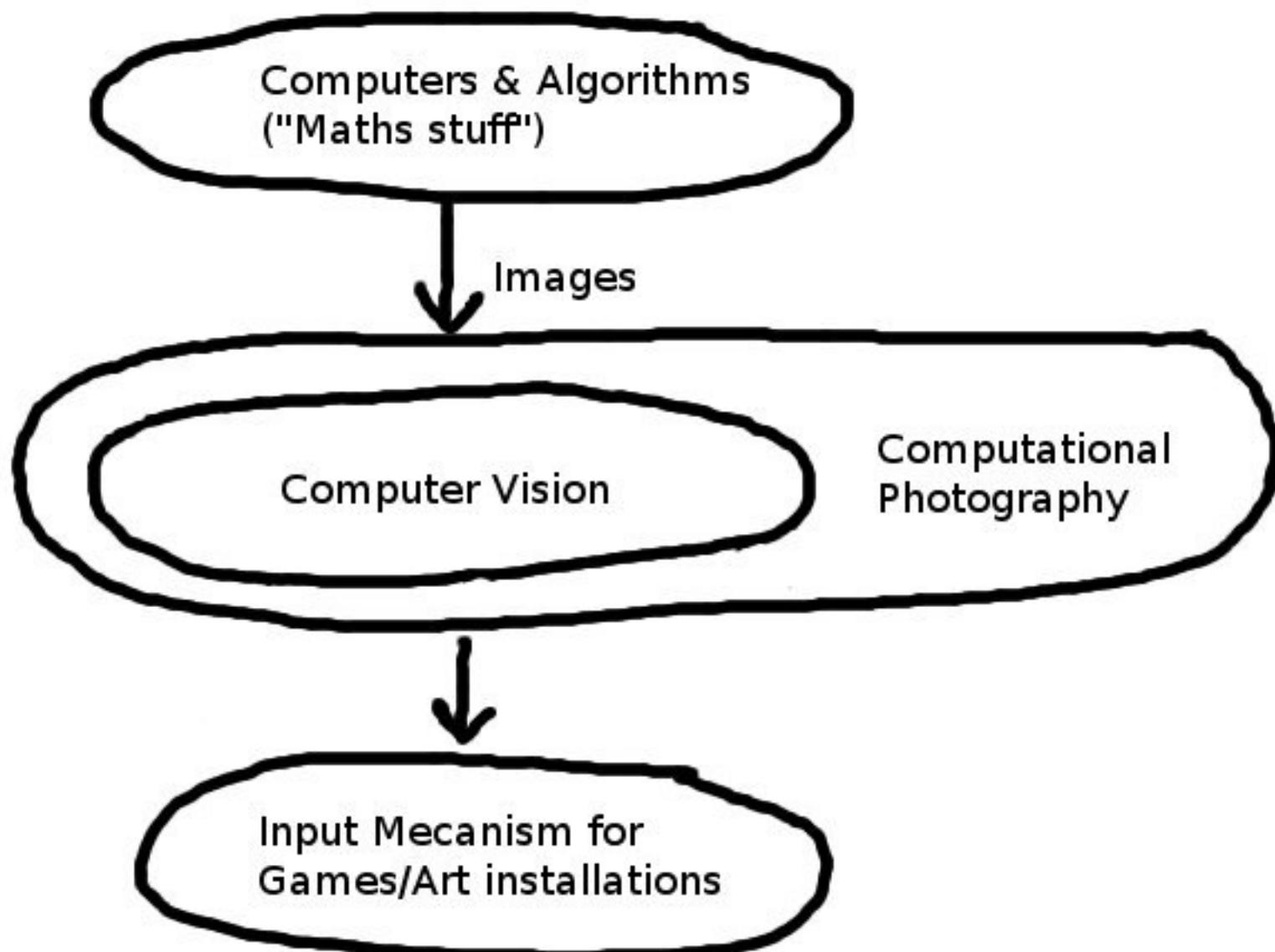
- this is a computer
- it runs software
- computer vision algorithms



# a map

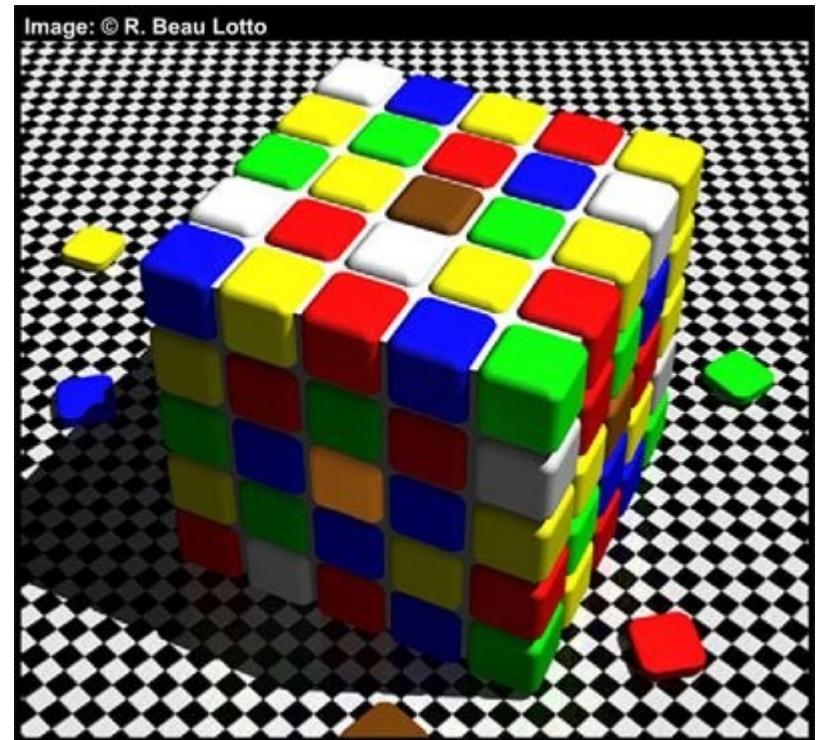


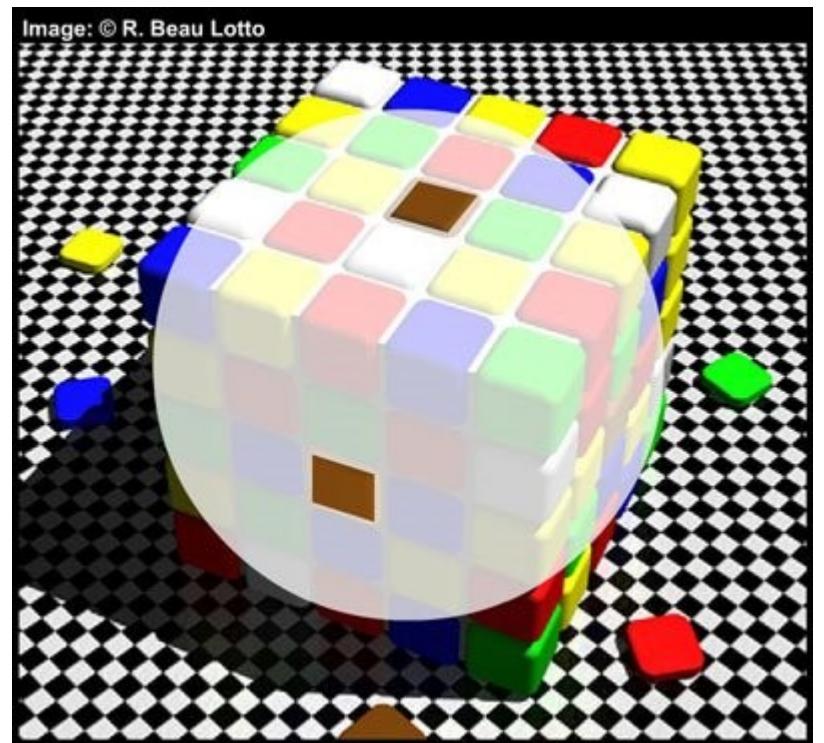
# a map



# what is computer vision?

- algorithmic understanding of images
- not anything to do with neuroscience
- it's all statistics
- vibrant research field



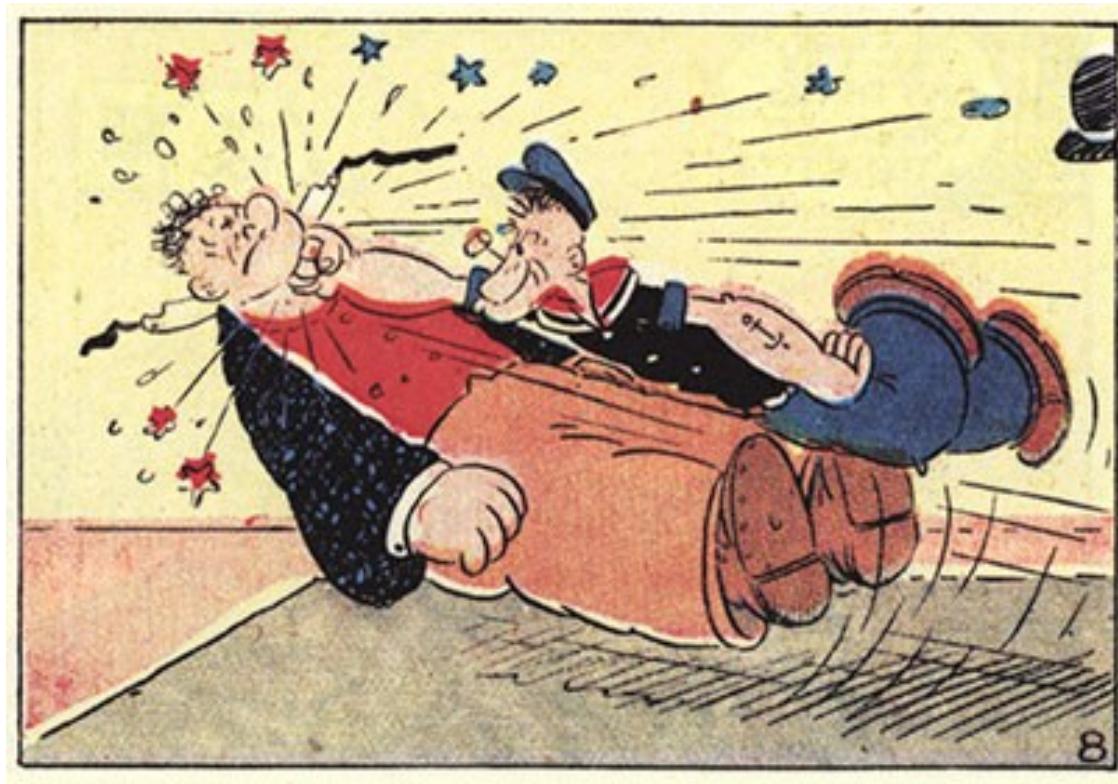


some examples



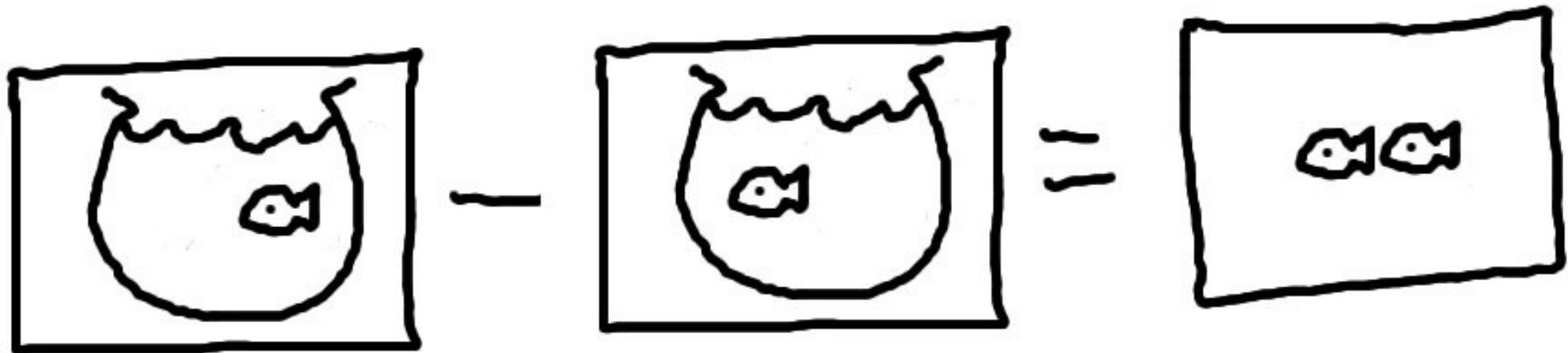
- Good computer vision library to get started with
- C++, Python
- Has a lot of algorithms “ready to use”
- Also good as an app framework – hardware abstraction
- <http://opencv.willowgarage.com/wiki/>

# motion detection



find all the things in an image sequence that are moving

# frame differencing



- take one image away from the other
- left with what's changed
- still things dissapear

# robust

- camera wobble
- lighting changes
- all EyeToy games use this technique



# background subtraction

- separate a person from the background of an image



# background subtraction

- take a reference image
- subtract from current image
- left with what is not in reference image



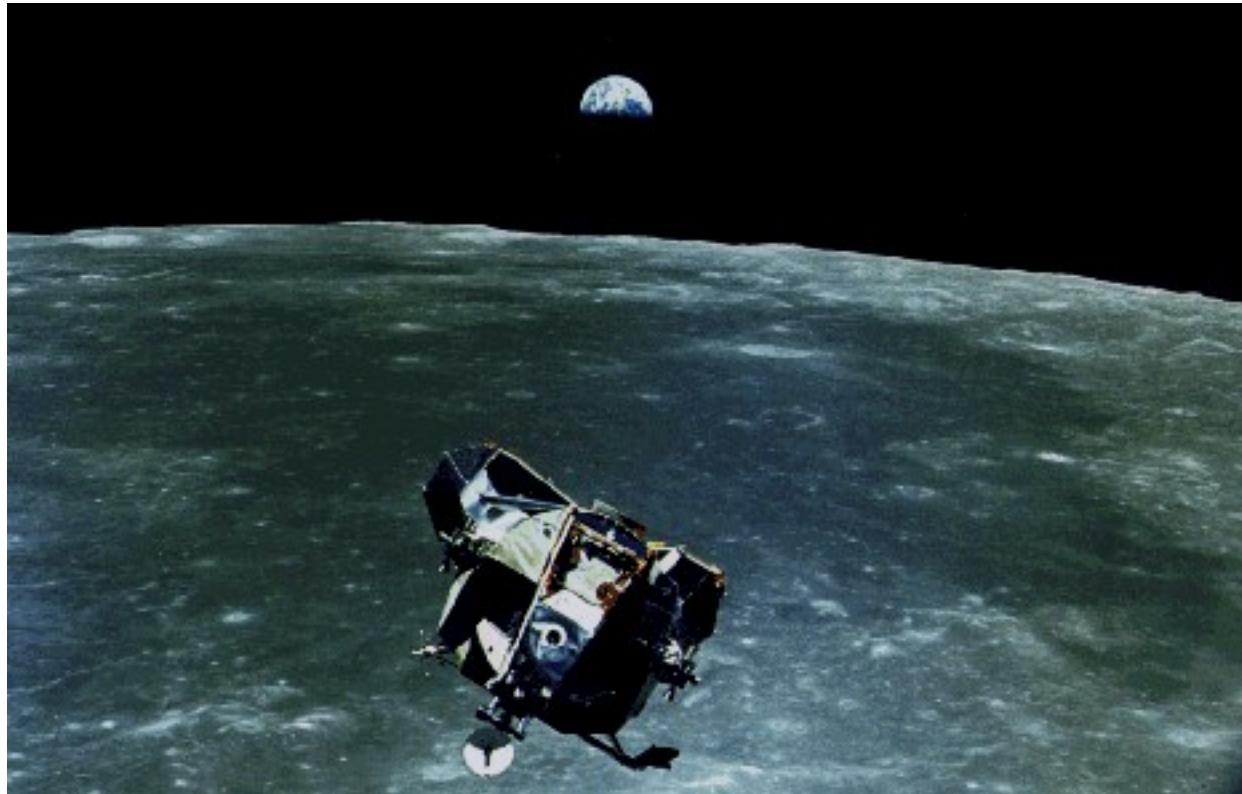
# not so robust



- time is a factor
- the longer it's running the worse it gets

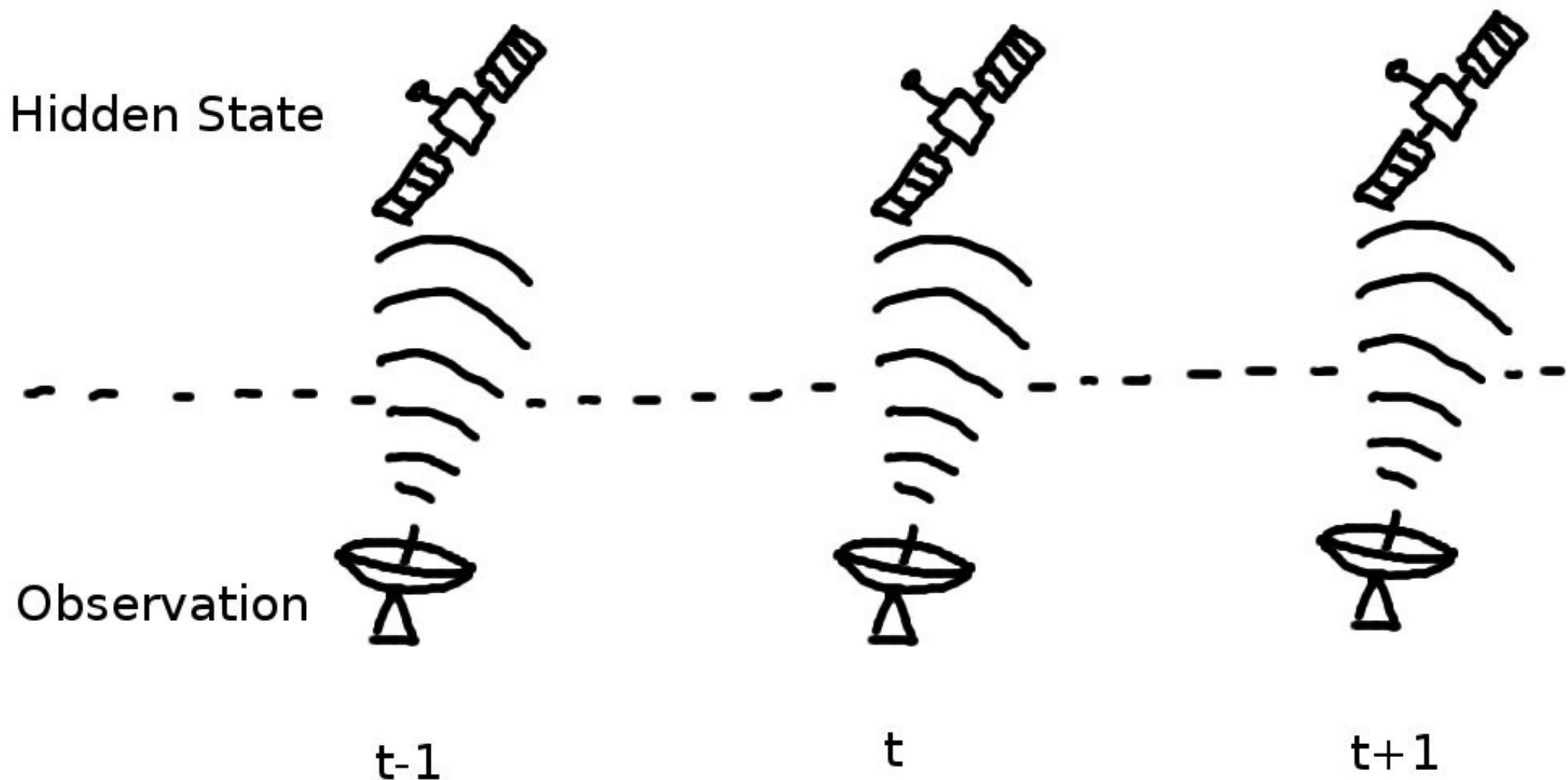
tracking things

# tracking objects

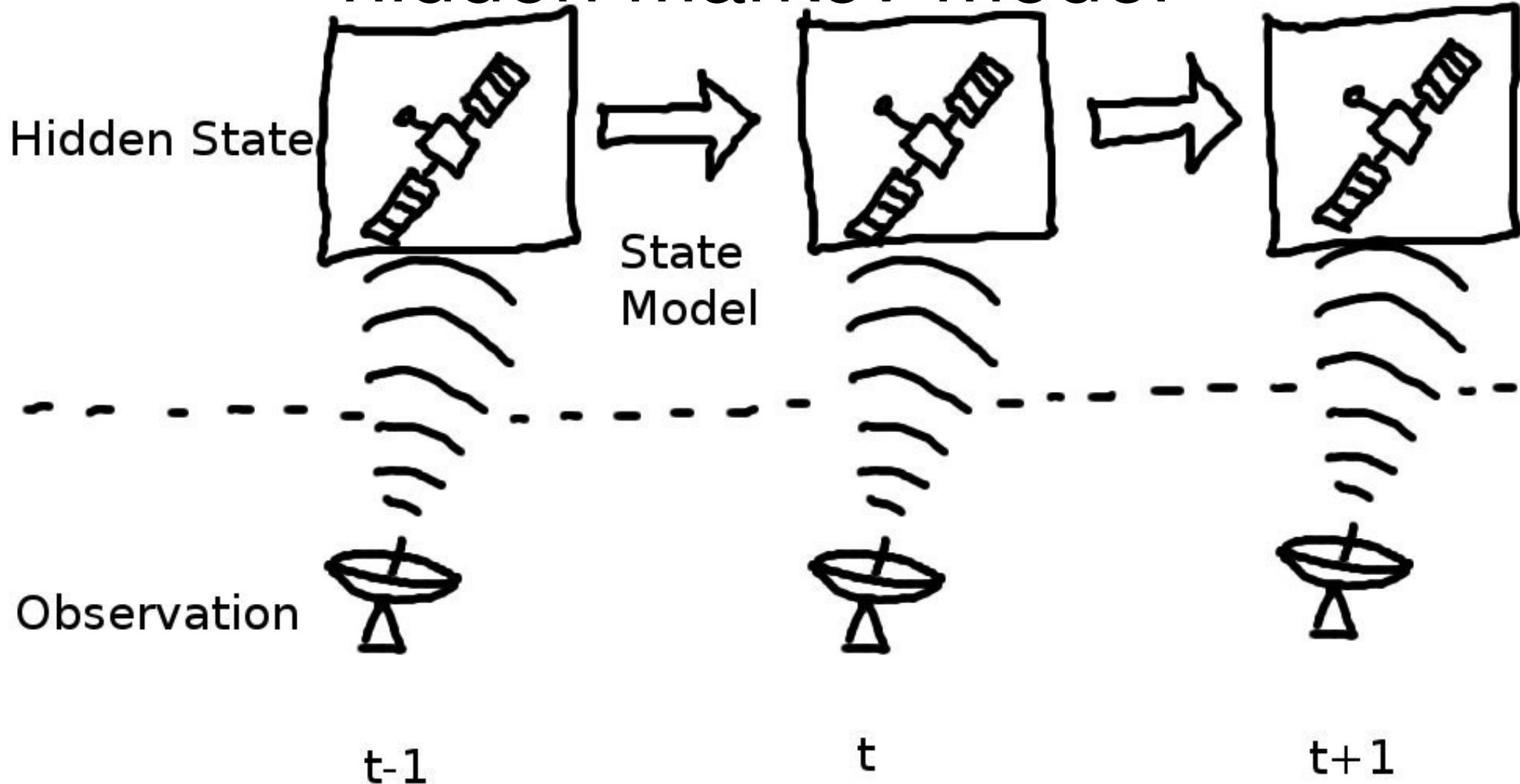


- tracking objects – kalman filter, particle filter
- Rudolf E. Kalman, used in the Apollo missions (1961)

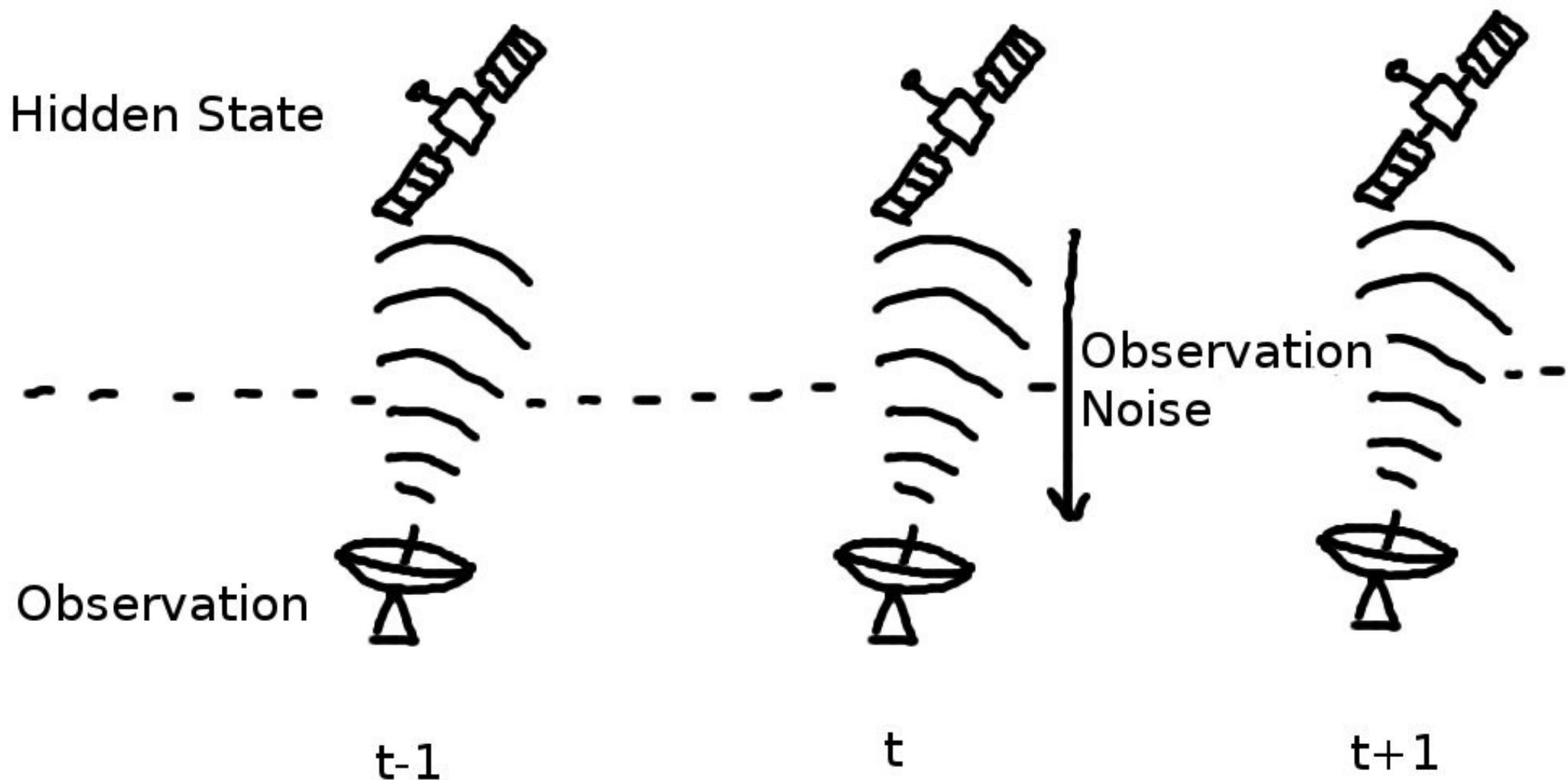
# hidden markov model



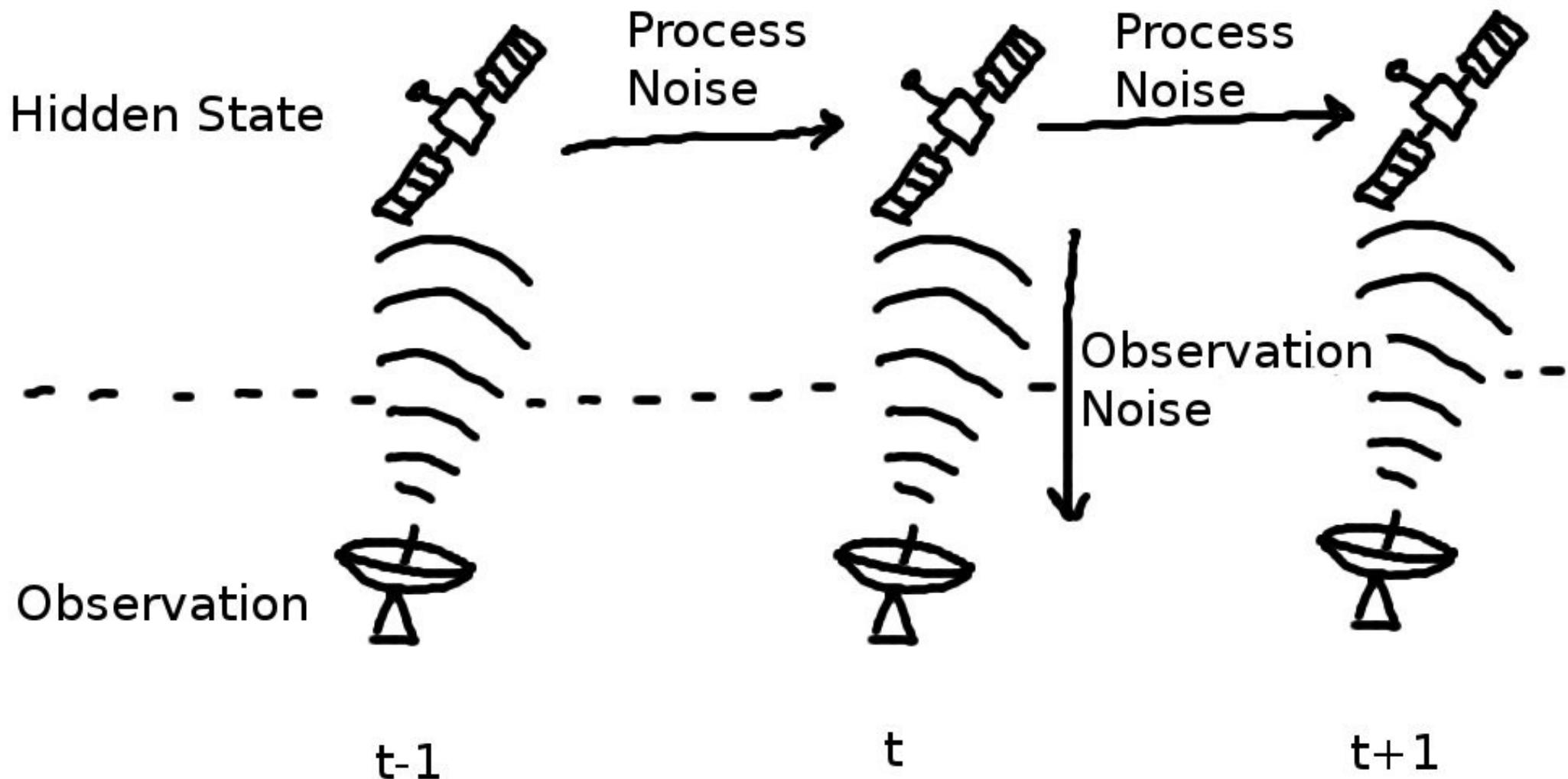
# hidden markov model



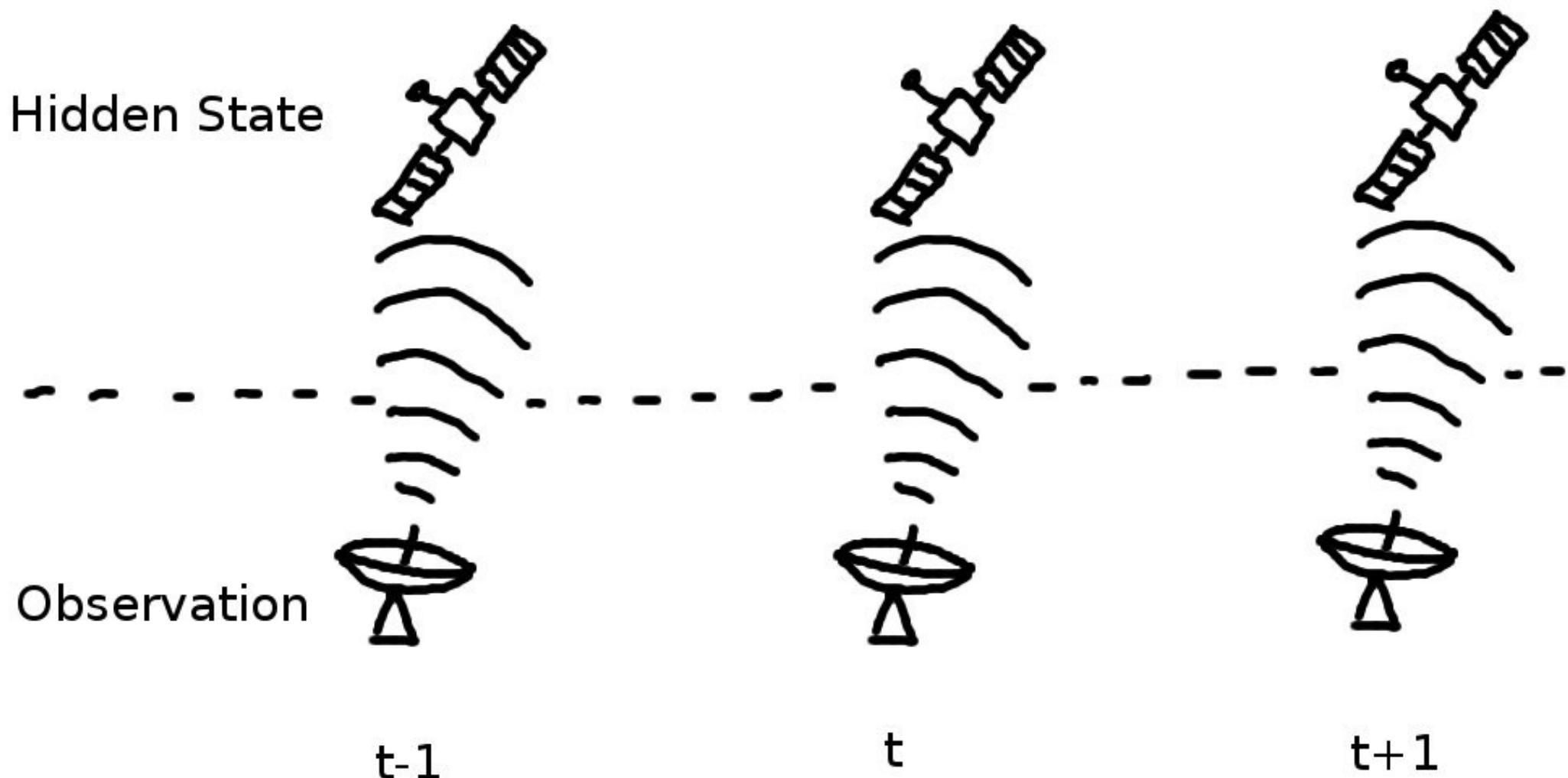
# hidden markov model



# hidden markov model



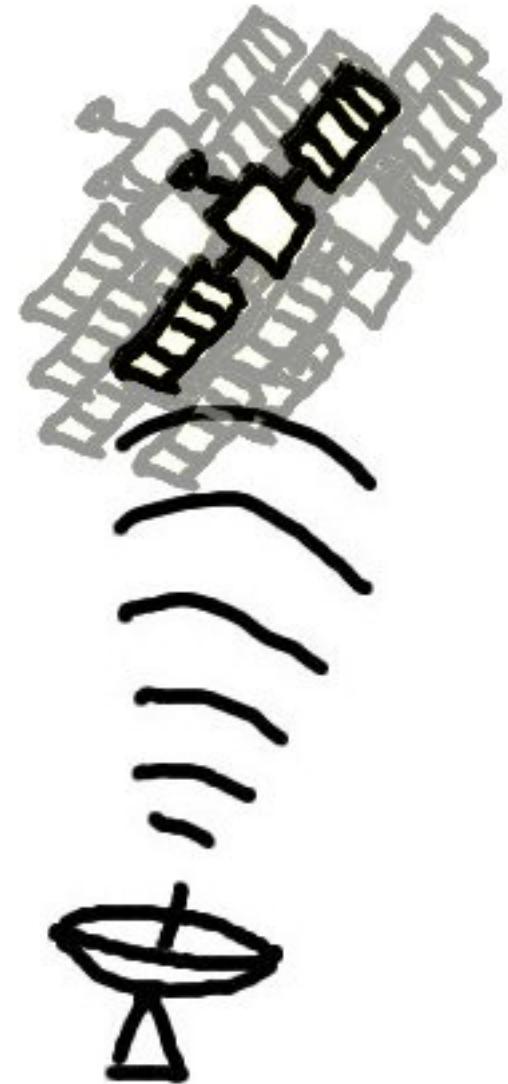
# hidden markov model



- Predict the next state
- Correct based on observation

# particle filter

- many estimates at once
- use each to predict the next step
- correct based on actual observation
- estimate is weighted average
- demo



faces

# faces

faces are good for computation photographers:

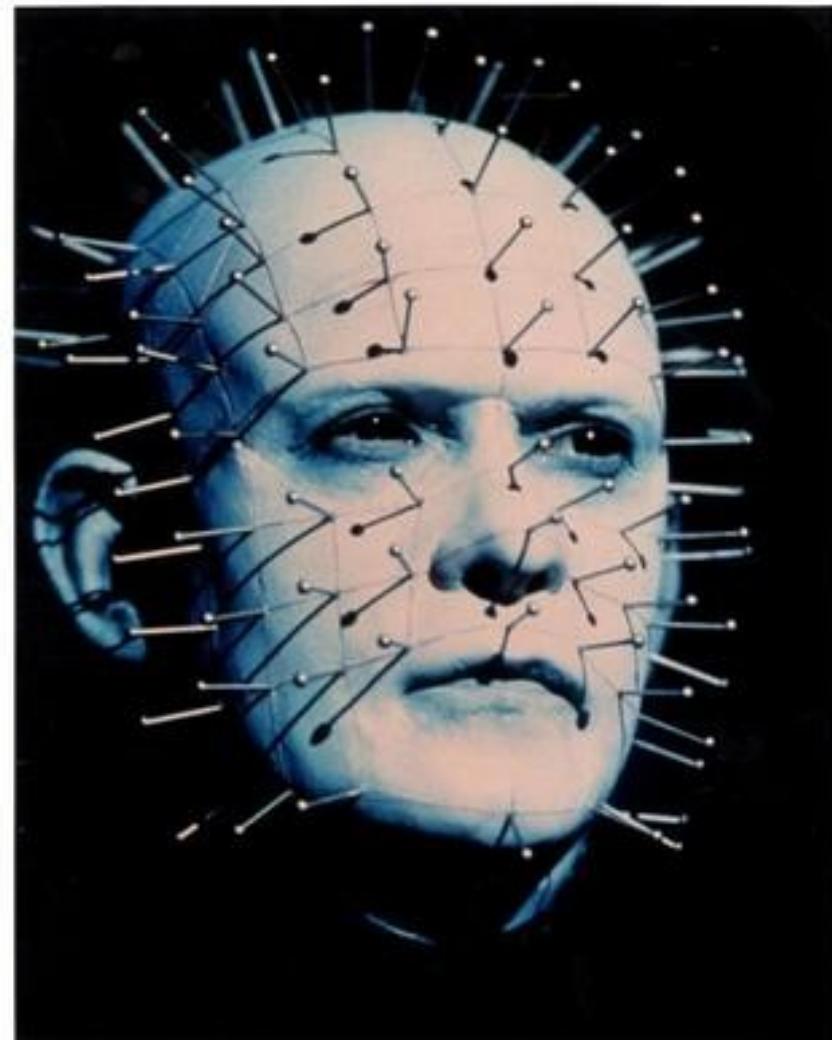
- most images have some in
- everyone has one
- we are highly attuned to understanding them
- there is lots of research in this field which as artists we can use (security industry!)

# face algorithms

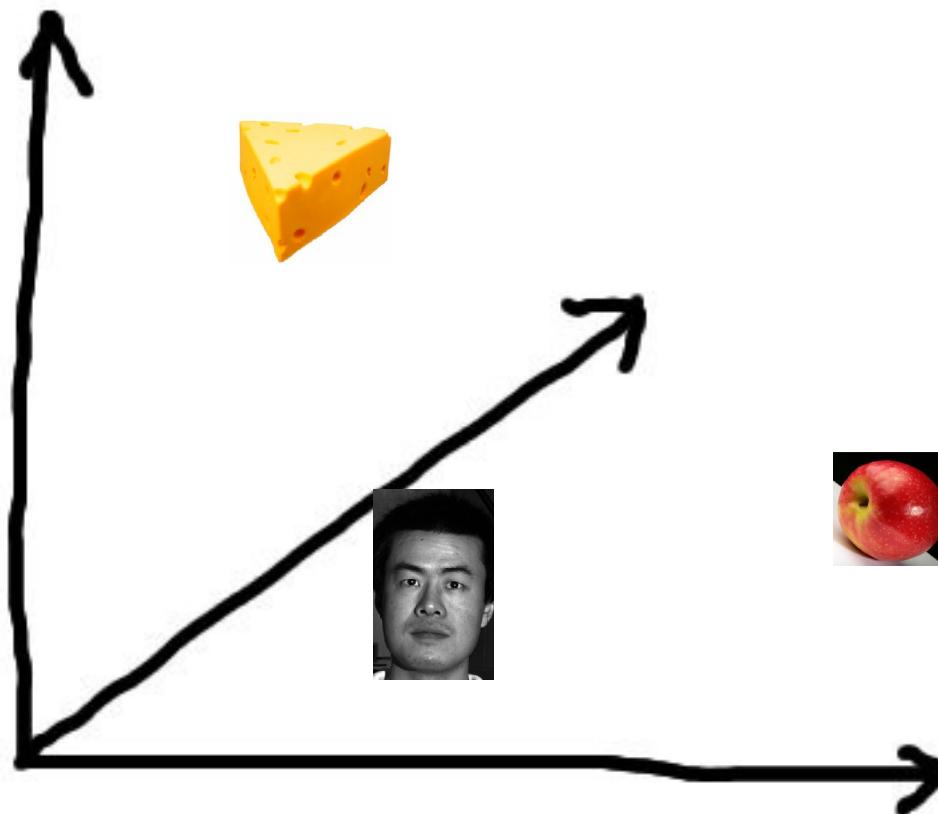
- face finding – locate faces in an image
- face recognition – who are they?

# what a face can tell you?

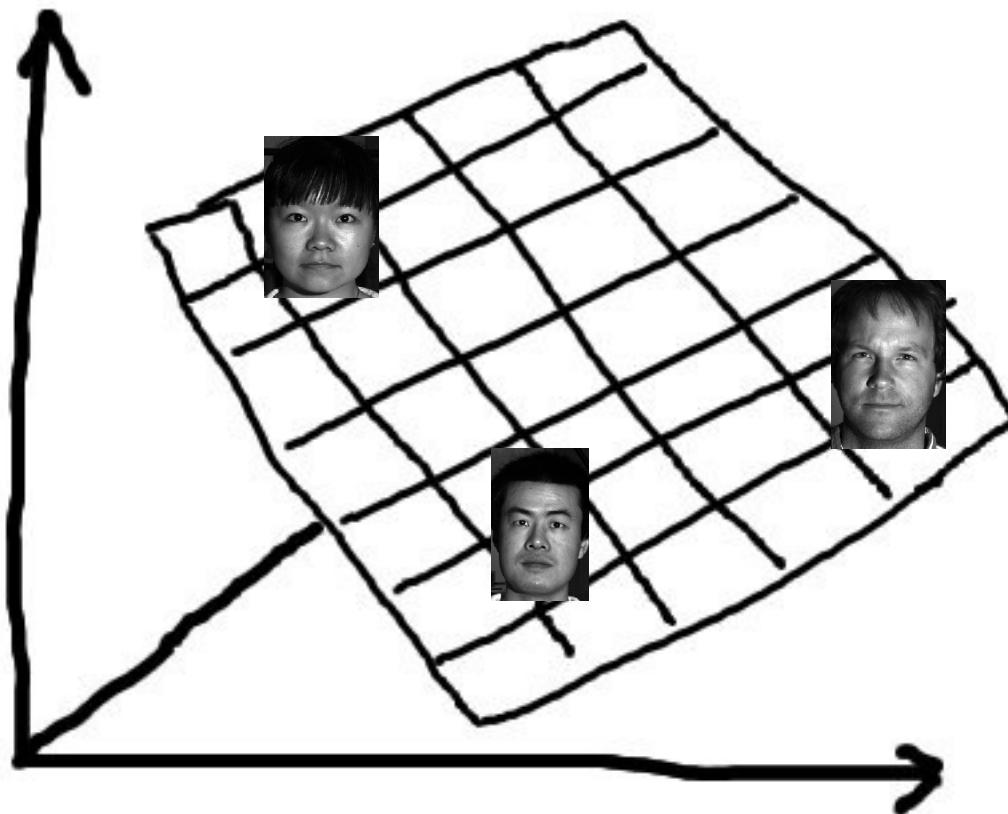
- Identity
- Expression
- Gender
- Ethnicity
- Pose
- Lighting



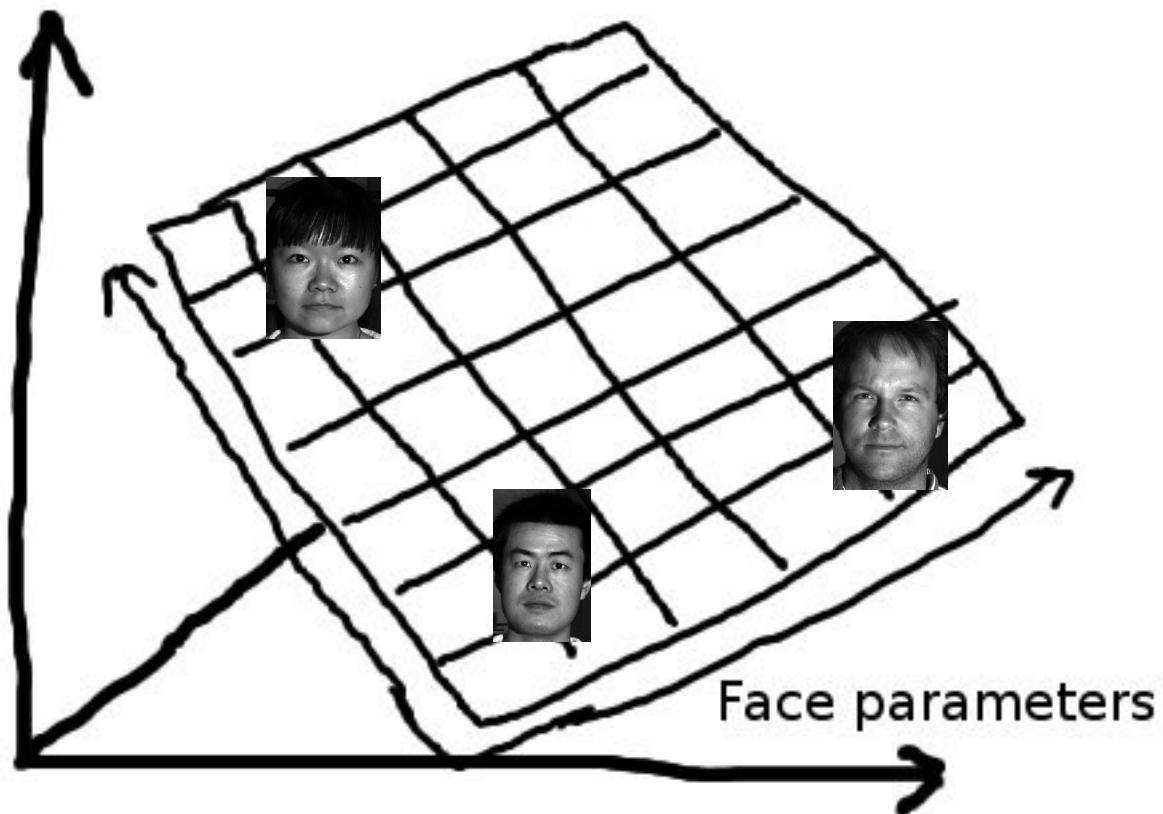
# space of all possible images



# image space contains a face space



# the axes have meaning



# how to make a face space



062\_1\_1.jpg 062\_2\_1.jpg 062\_3\_1.jpg 062\_4\_1.jpg 064\_1\_1.jpg 064\_2\_1.jpg 064\_3\_1.jpg 064\_4\_1.jpg 065\_1\_1.jpg 065\_2\_1.jpg



065\_3\_1.jpg 065\_4\_1.jpg 066\_1\_1.jpg 066\_2\_1.jpg 066\_3\_1.jpg 066\_4\_1.jpg 067\_1\_1.jpg 067\_2\_1.jpg 067\_3\_1.jpg 067\_4\_1.jpg



068\_1\_1.jpg 068\_2\_1.jpg 068\_3\_1.jpg 068\_4\_1.jpg 069\_1\_1.jpg 069\_2\_1.jpg 069\_3\_1.jpg 069\_4\_1.jpg 070\_1\_1.jpg 070\_2\_1.jpg



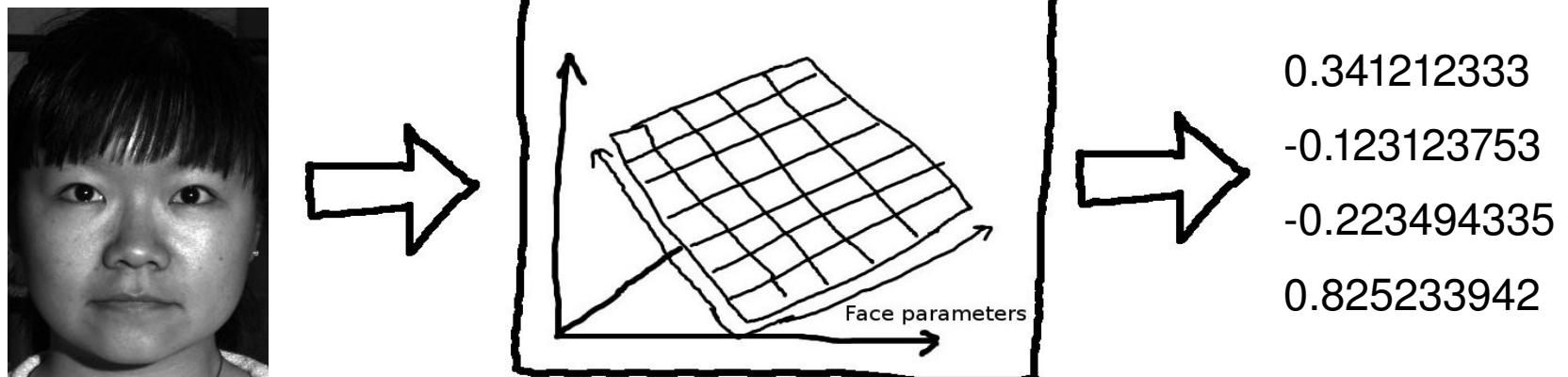
070\_3\_1.jpg 070\_4\_1.jpg 071\_1\_1.jpg 071\_2\_1.jpg 071\_3\_1.jpg 071\_4\_1.jpg 072\_1\_1.jpg 072\_2\_1.jpg 072\_3\_1.jpg 072\_4\_1.jpg



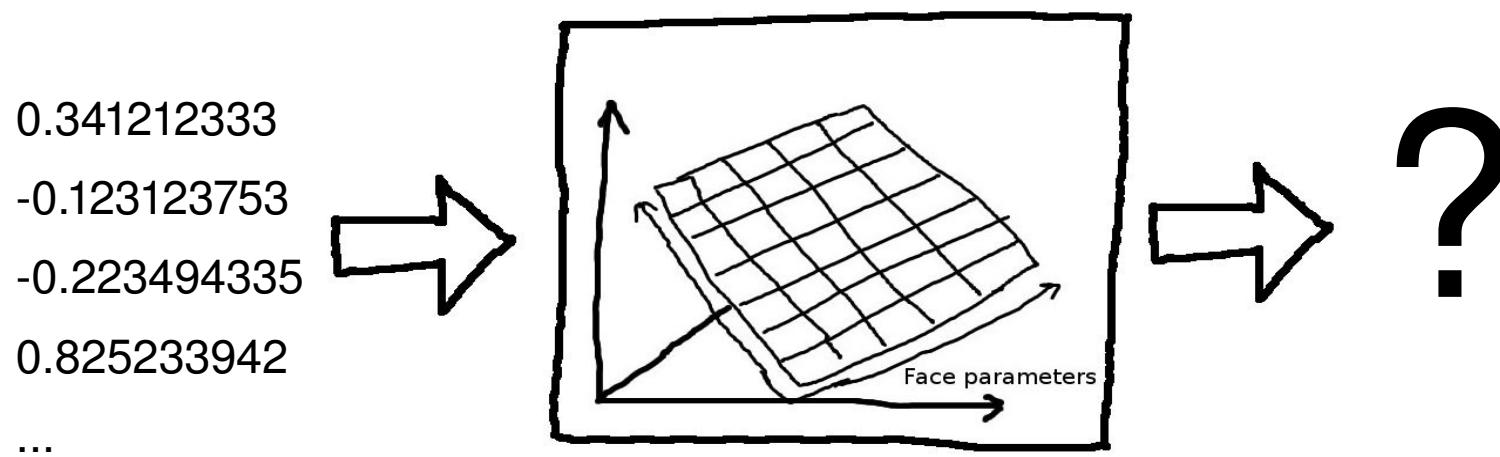
073\_1\_1.jpg 073\_2\_1.jpg 073\_3\_1.jpg 073\_4\_1.jpg 074\_1\_1.jpg 074\_2\_1.jpg 074\_3\_1.jpg 074\_4\_1.jpg 075\_1\_1.jpg 075\_2\_1.jpg



# understanding a face



# synthesising a new face

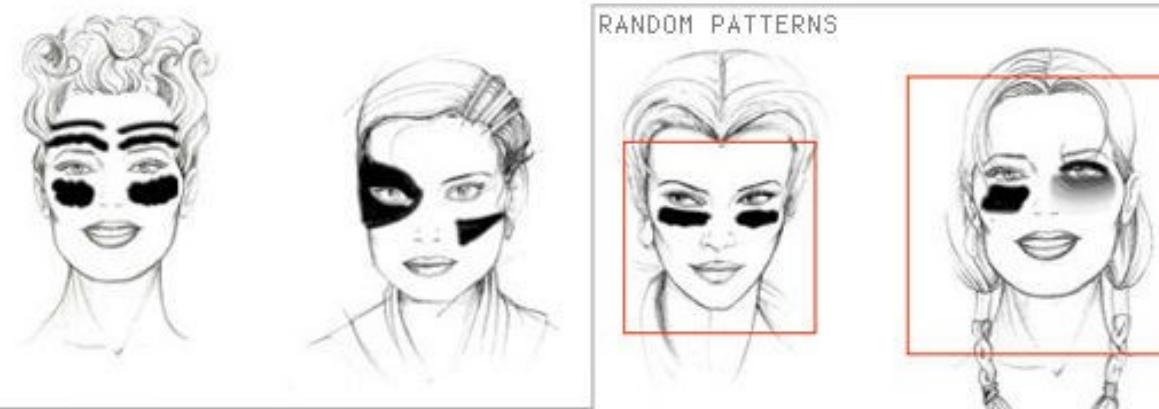


videos...

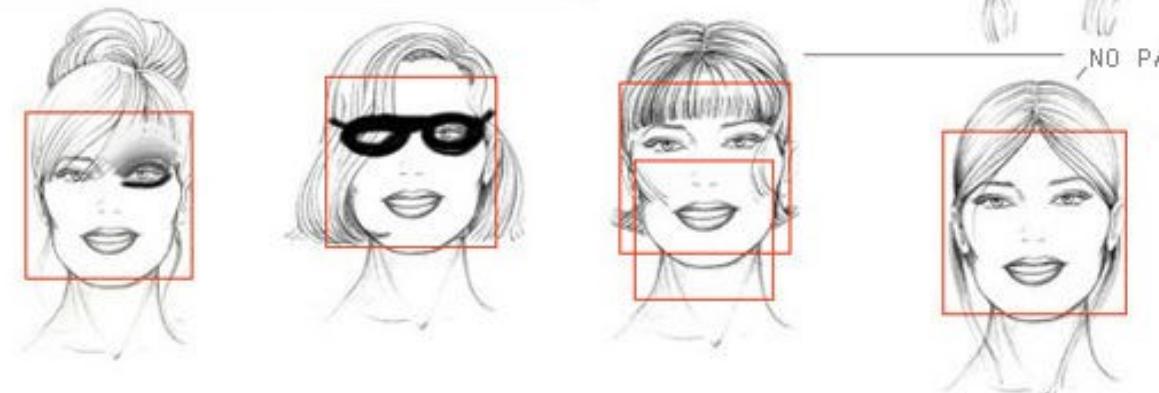
TEST PATTERNS



RANDOM PATTERNS

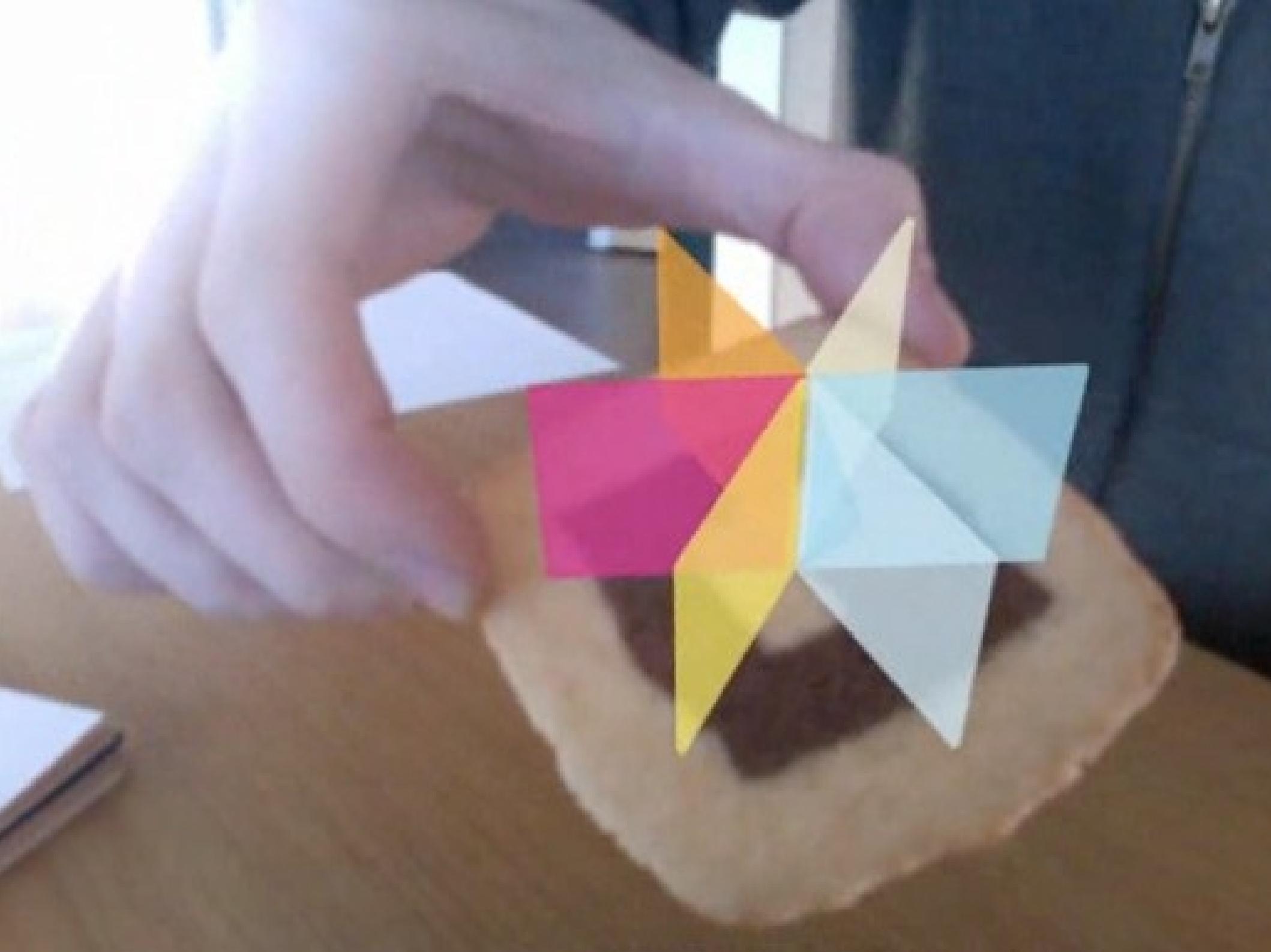


NO PATTERN



- CV Dazzle: Adam Harvey
- <http://ahprojects.com/c/itp/thesis>

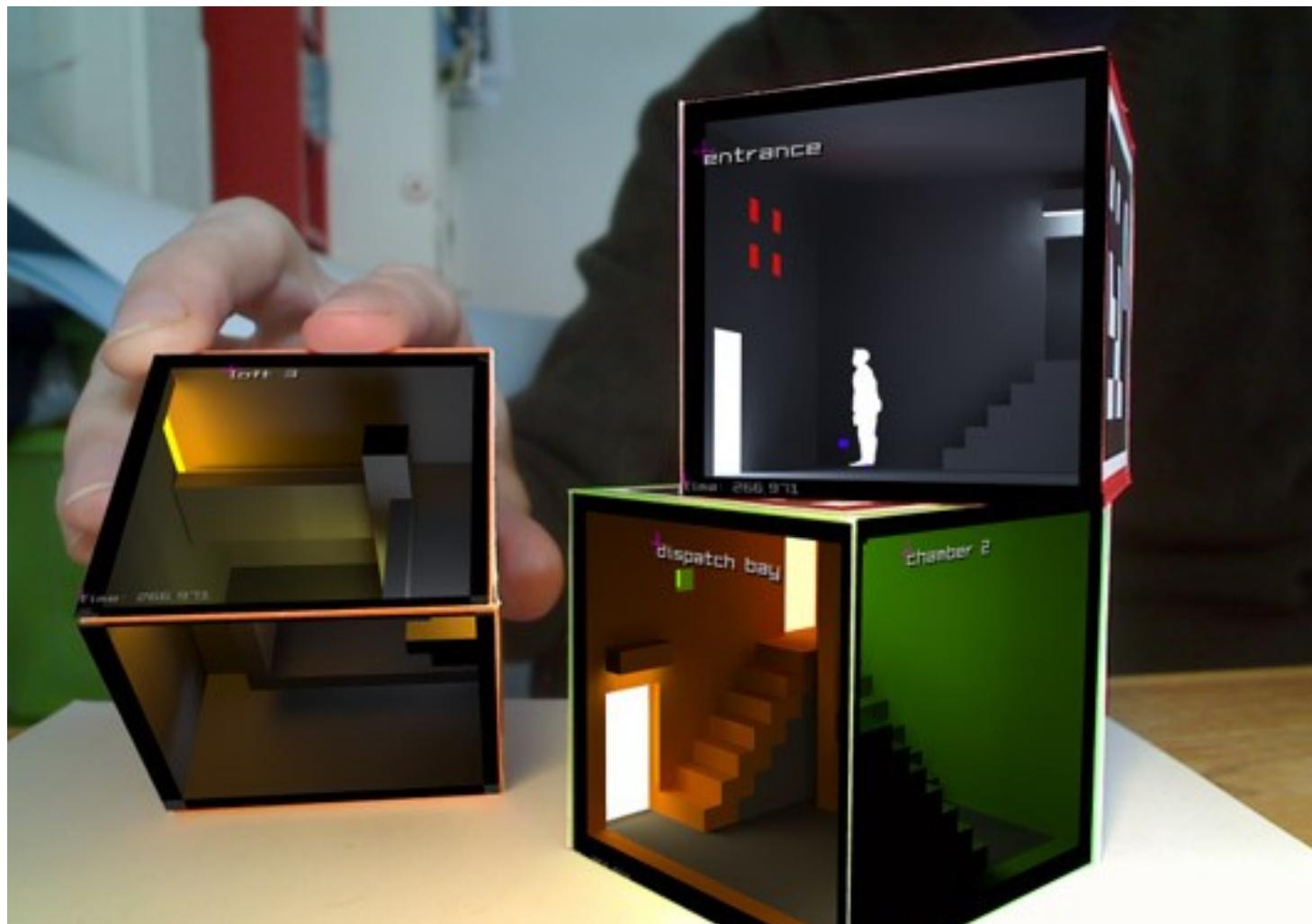
augmented reality





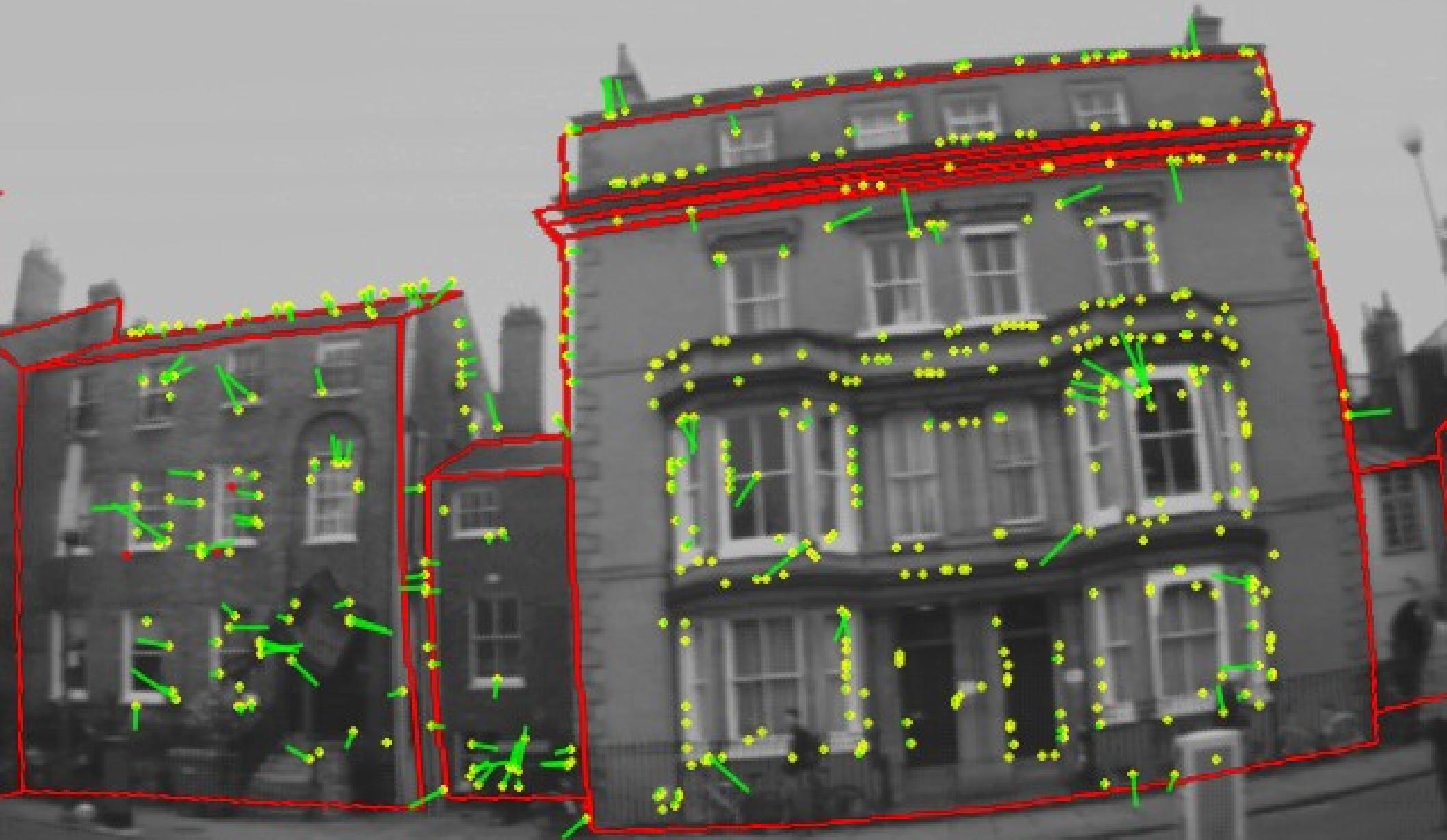
# levelhead by Julian Oliver

- <http://selectparks.net/~julian/levelhead/>
- arttoolkit:<http://www.hitl.washington.edu/artoolkit/>



# artvertiser



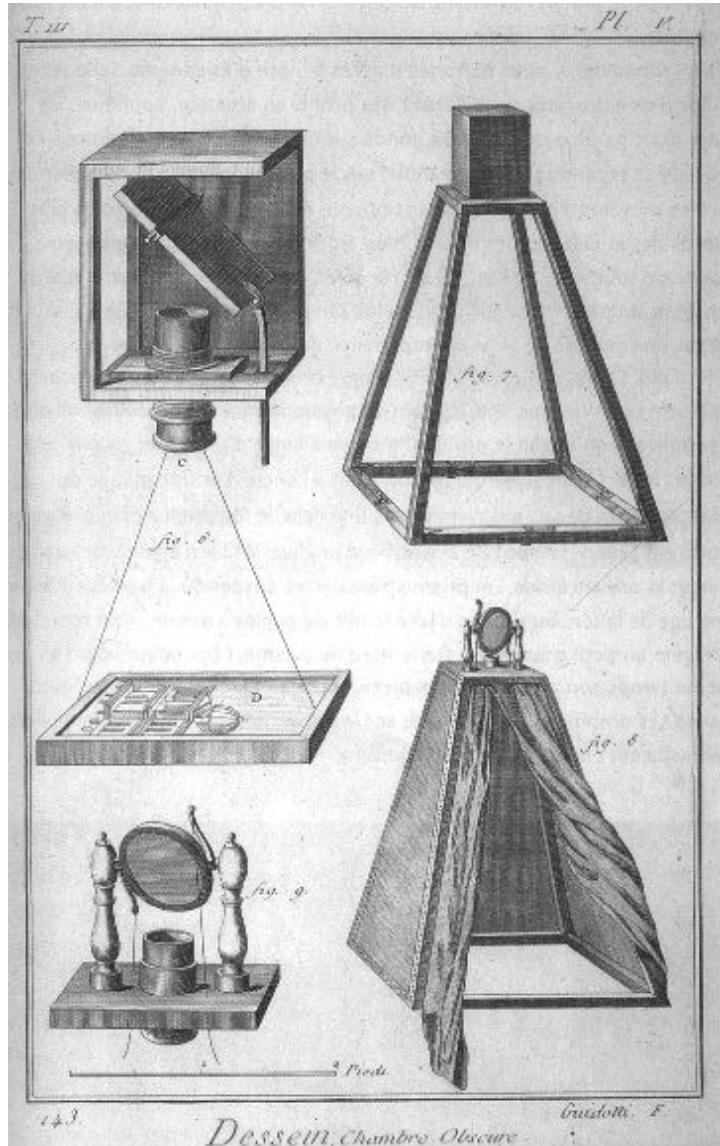


# Depth Cameras

- RGB-D per pixel
- Microsoft Natal/Kinect



# how can I use this as an artist?



- not difficult to get interesting things happening
- lots of code out there (free software/open source)
- think how you could (ab)use them artistically
- talk to researchers, use their stuff for art!

# links

- <http://trac.lirec.org/wiki/MagicSquares>
- <http://www.pawfal.org/dave>
- [dave@fo.am](mailto:dave@fo.am)
- <http://opencv.willowgarage.com/wiki/>
- <http://www.hitl.washington.edu/artoolkit/>